

Structural Integrity Monitoring using Guided Ultrasonic Waves



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NPL - May 2010

Overview



- Guided Ultrasonic Waves
- Large Area Structural Integrity Monitoring (SIM)
- Distributed Ultrasonic Sensors Array
- Defect Detection at a Stiffener
- Calculation of Scattering at Defect
- Defect Sensitivity Prediction
- Conclusions

Guided Ultrasonics

Guided Ultrasonic Wave Testing:

- Thin structure or layer
- Wave mode through thickness
- Propagation along plate
- Large area coverage
- A₀ Lamb Wave Mode
- Bending (Flexural) Wave
- Excitation using small
 Piezoelectric Transducer



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Mode Shapes at 0.8 MHz mm



-0.15

-0.2

-0.25

a) no defect

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15

-5

-15

-15

-10

b) with defect

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5

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Measurement at tensile specimen with circular fastener hole incident wave from left

-15

-15

-10

-5

 $f_0 = 40 \text{ kHz}, \lambda = 26 \text{ mm}, r_0 = 3.25 \text{ mm}, h = 3.17 \text{ mm}$

-0.2

-0.25

Distributed Sensors Array

- Distributed Sensors on Structure
- Point Source / Receiver for guided wave mode
- Propagation along plate
- Large area coverage
- Complexity of 'Baseline'
 - Multiple reflections
 - Edges and structural features
- Damage localization concept for SIM



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Distributed Sensors Array



Experimental time traces, plate with part-through slot Top: no defect; Center: defect; Bottom: difference signal

- Baseline Measurement
- 'Defect' Measurement
- Baseline Subtraction

- Removal of reflections at structural features
- Reduction of signal complexity
- Temperature Compensation
- Difference of Envelope
- Difference of Signal

Plate - Experiment





Schematic of aluminium plate (1.5m x 1m x 5 mm) 2 x 4 transducers, 28 pitch-catch time traces, 2 masses (glued)

Plate - Experiment

28 Signals



Damage map for 2 masses (glued), 20 dB scale, 2 pulses Addition of monitored signals - 'Probability of damage location'

Plate - Experiment



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Damage map for 2 masses (glued), 40 dB scale, 2 pulses Multiplication of monitored signals - 'Exclusion of damage location'

Example: Ship Hull

- Single or Double Hull
- Hull Plating (Mild Steel)
- Corrosive Environment
 - Seawater
 - Crude Oil (Sulphur)
- Depending on Treatment
 - General Corrosion
 - Corrosion Pitting
- Fatigue Cracks
- Often at Structural Features
 - Stiffeners
 - Web Frames





Stiffened Steel Plate





Steel Plate (mild steel): 2 m x 1 m x 5 mm Stiffener: 50 mm x 50 mm x 5 mm

Excitation: Transducer (Pz27, brass backing, D = 5 mm) Measurement: Polytec Laser Vibrometer





Schematic of steel plate (2m x 1m x 5 mm) with stiffener 2 x 6 transducers each side of stiffener, 66 pitch-catch time traces



Damage map for through notch (20 mm long), 40 dB scale Multiplication of measured signals on both sides of stiffener



Schematic of steel plate (2m x 1m x 5 mm) with stiffener 6 transducers on right side of stiffener, 15 pitch-catch time traces



Damage map for through notch (20 mm long), 20 dB scale Addition of measured signals on right side of stiffener



Damage map for through notch (20 mm long), 40 dB scale Multiplication of measured signals on right side of stiffener

Scattering Predictions

- Hybrid model to predict relative amplitudes of guided wave pulses
- Scattering amplitude and directivity from FE numerical calculation
- Verified from experiments
- Received defect pulse
 - Amplitude of incident wave at defect
 - Locally scattered amplitude from FE
 - Radial wave propagation
 - Amplitude decreases with $\approx \frac{1}{\sqrt{r}}$



Relative amplitude for distributed sensor array

Implications for SIM

- Distributed sensor array:
 - Assumption 20 mm long vertical through thickness crack
 - Calculate predicted defect pulse amplitude relative for sensor pair
 - For multiple sensors / pathways use algorithm for data fusion (e.g. addition)
 - Predicted amplitude ratio for 4 sensors
 - Comparison to array performance
 - Comparison to advance knowledge of stress state in structure (location & preferential direction of fatigue cracks)
 - Guidance for sensor placement



Conclusions

- Guided Ultrasonic Wave:
 - A₀ Lamb wave mode (low frequency)
 - Scattering at defects and structural features
 - FEM simulations and experiments
 - Variation defect size, location and orientation
 - Prediction of scattered wave amplitude & directivity
- Distributed arrays for Structural Integrity Monitoring:
 - Defects in large plate structures
 - Detection and localization
 - Prediction for minimum detectable crack size
 - Guidance for number and placement of sensors

Acknowledgments

- Partially funded by UK Engineering and Physical Sciences Research Council (EPSRC)
- Thanks to students and researchers who contributed to this work:
 - Dr. Bernard Masserey
 - Erik Kostson
 - Clemence Rouge
 - Robert Watson